

273(3): Calculation of orbital linear Velocity with 3-D Theory.

The orbital linear velocity in 3-D theory is defined

by 
$$\underline{v} = \dot{r} \underline{e}_r + r \dot{\theta} \underline{e}_\theta + r \dot{\phi} \sin \theta \underline{e}_\phi \quad - (1)$$

so 
$$v^2 = \dot{r}^2 + r^2 (\dot{\theta}^2 + \dot{\phi}^2 \sin^2 \theta) \quad - (2)$$

In the 2-D theory:

$$v^2 = \dot{r}^2 + r^2 \dot{\phi}^2 \quad - (3)$$

$$= \left( \frac{dr}{dt} \right)^2 + r^2 \left( \frac{d\phi}{dt} \right)^2$$

In the 2-D theory:

$$\omega = \frac{d\phi}{dt} = \frac{L_z}{mr^2} \quad - (4)$$

and

$$\frac{dr}{dt} = \frac{dr}{d\phi} \frac{d\phi}{dt} \quad - (5)$$

So 
$$v^2 = \frac{L_z^2}{m^2 r^2} + \left( \frac{dr}{d\phi} \right)^2 \left( \frac{d\phi}{dt} \right)^2$$

$$= \frac{L_z^2}{m^2 r^2} \left( 1 + \frac{1}{r^2} \left( \frac{dr}{d\phi} \right)^2 \right) \quad - (6)$$

In this expression:

$$2) \left( \frac{dr}{d\phi} \right)^2 = \frac{\epsilon^2 r^4}{d^2} \left( 1 - \cos^2 \phi \right) \quad - (7)$$

where  $\cos^2 \phi = \frac{1}{\epsilon^2} \left( \frac{d}{r} - 1 \right)^2 \quad - (8)$

So:  $v^2 = \frac{L^2}{m^2} \left( \frac{1}{r^2} + \frac{\epsilon^2}{d^2} \left( 1 - \frac{1}{\epsilon^2} \left( \frac{d}{r} - 1 \right)^2 \right) \right)$

$$= \frac{L^2}{m^2 d} \left( \frac{\epsilon^2 - 1}{d} + \frac{2}{r} \right)$$

$$= \frac{L^2}{m^2 d} \left( \frac{2}{r} - \frac{1}{a} \right) \quad - (9)$$

$$= M_1 G \left( \frac{2}{r} - \frac{1}{a} \right)$$

In the 3-D theory:

$$v^2 = \left( \frac{dr}{dt} \right)^2 + r^2 \left( \frac{d\beta}{dt} \right)^2 \quad - (10)$$

and  $\omega = \frac{d\beta}{dt} = \frac{L}{m r^2} \quad - (11)$

A direct comparison of eqs. (3) and (10) can

be made, and graphed.

## 2-D Theory

In this case:

$$\dot{r} = \left( \frac{2}{m} \left( E - \frac{L_z^2}{2mr^2} + \frac{k}{r} \right) \right)^{1/2} \quad (12)$$

where

$$r = \frac{d}{1 + \epsilon \cos \phi} \quad (13)$$

and

$$\dot{\phi} = \frac{L_z}{mr^2} \quad (14)$$

So v can be graphed as a function of  $\phi$ .

In this case:

$$v^2 = \dot{r}^2 + r^2 (\dot{\theta}^2 + \dot{\phi}^2 \sin^2 \theta) \quad (15)$$

where:

$$\dot{r} = \left( \frac{2}{m} \left( E - \frac{L^2}{2mr^2} + \frac{k}{r} \right) \right)^{1/2} \quad (16)$$

$$\dot{\phi} = \frac{L_z}{mr^2 \sin^2 \theta} \quad (17)$$

$$\dot{\theta} = \frac{1}{mr^2} \left( L^2 - \frac{L_z^2}{\sin^2 \theta} \right)^{1/2} \quad (18)$$

$$r = \frac{d}{1 + \epsilon \cos \beta} \quad (19)$$

$$4) \cos \beta = \frac{\cos \phi}{\left( \cos^2 \phi + \left( \frac{L_z}{L} \right)^2 \sin^2 \phi \right)^{1/2}} \quad - (20)$$

and

$$\sin^2 \theta = \left( \frac{L_z}{L} \right)^2 + \left( 1 - \left( \frac{L_z}{L} \right)^2 \right) \left( \frac{\cos^2 \phi}{\cos^2 \phi + \left( \frac{L_z}{L} \right)^2 \sin^2 \phi} \right) \quad - (21)$$

So  $v$  can equally be expressed as a function of  $\phi$  using the chain of equations (15) to (21). So a direct comparison of the 2-D and 3-D theories can be made.

Another type of direct comparison can be made with:

$$v^2 = \frac{L^2}{n^2 r^2} \left( 1 + \frac{1}{r^2} \left( \frac{dr}{d\beta} \right)^2 \right) \quad - (22)$$

Now we:

$$\frac{dr}{d\beta} = \frac{dr}{d\phi} \frac{d\phi}{d\beta} \quad - (23)$$

where:

$$\frac{d\phi}{d\beta} = \frac{Lz}{L \sin^2 \theta} \quad (24)$$

This means that:

$$v^2 = \frac{L^2}{m^2 r^2} \left( 1 + \frac{y^2}{r^2} \left( \frac{dr}{d\phi} \right)^2 \right) \quad (25)$$

where

$$y = \frac{Lz}{L \sin^2 \theta} \quad (26)$$

Comparison of Eqs. (6) and (25) gives a direct comparison of the 2-D and 3-D theories.

It is seen that in the 3-D theory  $Lz$  in eq. (6) is replaced by  $L$ , and  $dr/d\phi$  is replaced by  $y dr/d\phi$ . The easiest way of making this comparison is to use eq. (22) and eq. (19). It follows that:

$$\left( \frac{dr}{d\beta} \right)^2 = \frac{c^2 r^4}{d^2} (1 - \cos^2 \beta) \quad (27)$$

where

$$\cos^2 \beta = \frac{1}{c^2} \left( \frac{d}{r} - 1 \right) \quad (28)$$

6) So is direct analogy to eqs. (7) to (9):

$$v^2 = mG \left( \frac{2}{r} - \frac{1}{a} \right) \quad (29)$$

from the 3-D theory. However:

$$\frac{1}{a} = \frac{1 - e^2}{d} \quad (30)$$

$$= \frac{2E}{k}$$

So the difference between the 2-D and 3-D theories comes down to the difference in the total energy  $E$  in 2-D and 3-D.

The difference is made clear <sup>only</sup> by comparing

the graphs of  $v$  against  $\phi$ . In 2-D use eqs. (10) to (14), and in 3-D use eqs. (15) to (21).

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