

500(3) : Solutions for  $\underline{\omega}$  and  $\underline{Q}$

Consider the symmetry conditions :

$$(\partial_2 + \omega_2) Q_3 = -(\partial_3 + \omega_3) Q_2 \quad - (1)$$

$$(\partial_3 + \omega_3) Q_1 = -(\partial_1 + \omega_1) Q_3$$

$$(\partial_1 + \omega_1) Q_2 = -(\partial_2 + \omega_2) Q_1$$

In Cartesian notation these become:

$$\left( \frac{\partial}{\partial y} - \omega_y \right) Q_z = - \left( \frac{\partial}{\partial z} - \omega_z \right) Q_y$$

$$\left( \frac{\partial}{\partial z} - \omega_z \right) Q_x = - \left( \frac{\partial}{\partial x} - \omega_x \right) Q_z \quad - (2)$$

$$\left( \frac{\partial}{\partial x} - \omega_x \right) Q_y = - \left( \frac{\partial}{\partial y} - \omega_y \right) Q_x$$

Using :

$$\underline{\Omega} = \underline{\nabla} \times \underline{Q} - \underline{\omega} \times \underline{Q} \quad - (3)$$

and

$$\underline{\nabla} \cdot \underline{\Omega} = 0 \quad - (4)$$

it is found that

$$\underline{\nabla} \cdot (\underline{\omega} \times \underline{Q}) = 0 \quad - (5)$$

i.e.

$$\underline{Q} \cdot \underline{\nabla} \times \underline{\omega} = \underline{\omega} \cdot \underline{\nabla} \times \underline{Q} \quad - (6)$$

$$\begin{aligned} \text{i.e. } & Q_x \left( \frac{\partial \omega_z}{\partial y} - \frac{\partial \omega_y}{\partial z} \right) + Q_y \left( \frac{\partial \omega_x}{\partial z} - \frac{\partial \omega_z}{\partial x} \right) + Q_z \left( \frac{\partial \omega_y}{\partial x} - \frac{\partial \omega_x}{\partial y} \right) \\ &= \omega_x \left( \frac{\partial Q_z}{\partial y} - \frac{\partial Q_y}{\partial z} \right) + \omega_y \left( \frac{\partial Q_x}{\partial z} - \frac{\partial Q_z}{\partial x} \right) + \omega_z \left( \frac{\partial Q_y}{\partial x} - \frac{\partial Q_x}{\partial y} \right) \end{aligned}$$

2) Eqs. (2) and (7) give five equations in six unknowns:  $\omega_x, \omega_y, \omega_z, Q_x, Q_y, Q_z$ . One more equation at least is needed for a complete solution.

Using:

$$\underline{g} = -\underline{\nabla} \underline{\Phi} + \underline{\omega} \underline{\Phi} = -\frac{\partial \underline{Q}}{\partial t} - \underline{\omega}_0 \underline{Q} \quad (8)$$

and

$$\underline{\nabla} \cdot \underline{g} = 4\pi \epsilon_0 \rho_m \quad (9)$$

it is found that:

$$\underline{\nabla} \cdot \left( \frac{\partial \underline{Q}}{\partial t} - \underline{\omega}_0 \underline{Q} \right) = -4\pi \epsilon_0 \rho_m \quad (10)$$

Now assume that:

$$\underline{\omega} = (0, \underline{\omega}) \quad (11)$$

so

$$\underline{\nabla} \cdot \frac{\partial \underline{Q}}{\partial t} = -4\pi \epsilon_0 \rho_m \quad (12)$$

i.e

$$\frac{\partial}{\partial t} (\underline{\nabla} \cdot \underline{Q}) = -4\pi \epsilon_0 \rho_m \quad (13)$$

$$\frac{\partial}{\partial t} \left( \frac{\partial Q_x}{\partial x} + \frac{\partial Q_y}{\partial y} + \frac{\partial Q_z}{\partial z} \right) = -4\pi \epsilon_0 \rho_m \quad (14)$$

So there are six equations in six unknowns,  $\omega_x, \omega_y, \omega_z, Q_x, Q_y, Q_z$ . These are eqs. (2),

3) (7) and (14).

Eq. (11) is similar to (except for the so called metric gauge in electrodynamics:

$$A^\mu = (0, \underline{A}) \quad - (15)$$

In order to avoid the use of the metric gauge, use may be made of the Lagrangian:

$$\begin{aligned} \mathcal{L} &= -\frac{mc^2}{\gamma} + \frac{m\mathbf{v} \cdot \mathbf{A}}{(x^2 + y^2 + z^2)^{1/2}} \quad - (16) \\ &= -\frac{mc^2}{\gamma} + \frac{m\mathbf{v} \cdot \mathbf{A}}{|\underline{r}|} \end{aligned}$$

in three dimensions. Here:

$$\gamma = \left(1 - \frac{v_0^2}{c^2}\right)^{-1/2} \quad - (17)$$

where

$$v_0^2 = \underline{\dot{r}} \cdot \underline{\dot{r}} = \dot{x}^2 + \dot{y}^2 + \dot{z}^2 \quad - (18)$$

There are two possible sets of Euler Lagrange eqns.

1) 
$$\frac{d\mathcal{L}}{d\underline{r}} = \frac{d}{dt} \frac{d\mathcal{L}}{d\underline{\dot{r}}} \quad - (19)$$

which produces:

$$\underline{F} = \gamma^3 m \underline{\ddot{r}} = -\frac{m\mathbf{v} \cdot \mathbf{A}}{r^3} \quad - (20)$$

and as in UFT 377 and

2) 
$$\underline{g} = \underline{\ddot{r}} = \frac{m\mathbf{v}}{\gamma r^3} \left( \frac{\underline{\dot{r}} (\underline{\dot{r}} \cdot \underline{r})}{c^2} - \underline{r} \right) \quad - (21)$$

4) Eq. (21) is stated form:

$$\frac{\partial \mathcal{L}}{\partial x} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}} \quad - (22)$$

$$\frac{\partial \mathcal{L}}{\partial y} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{y}} \quad - (23)$$

$$\frac{\partial \mathcal{L}}{\partial z} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{z}} \quad - (24)$$

and

$$\mathcal{L} = -mc^2 \left( 1 - \frac{\dot{x}^2 + \dot{y}^2 + \dot{z}^2}{c^2} \right)^{1/2} + \frac{2MG}{(x^2 + y^2 + z^2)^{1/2}} \quad - (25)$$

Eq. (20) gives retrograde precession and eq. (21) gives forward precession.

Evaluation of Spin Corrections

For retrograde precession:

$$\underline{g} = \gamma^3 \underline{\ddot{r}} = -MG \frac{\underline{r}}{r^3} = -\underline{\nabla} \Phi + \underline{\omega} \times \underline{r}$$

$$= -\frac{\partial \mathcal{Q}}{\partial \underline{r}} - \underline{\omega} \cdot \underline{r} \quad - (26)$$

For forward precession:

$$\underline{g} = \underline{\ddot{r}} = \frac{MG}{\gamma r^3} \left( \frac{\underline{\dot{r}} (\underline{\dot{r}} \cdot \underline{r})}{c^2} - \underline{r} \right)$$

$$= -\underline{\nabla} \Phi + \underline{\omega} \times \underline{r} = -\frac{\partial \mathcal{Q}}{\partial \underline{r}} - \underline{\omega} \cdot \underline{r} \quad - (27)$$

5) If the potential is approximated by:

$$\underline{\Phi} = \frac{-mG}{(x^2 + y^2 + z^2)^{1/2}} = -\frac{mG}{r} \quad (28)$$

Here the three components of  $\underline{\omega}$  can be found.

Eqs. (2) then give the three components of  $\underline{Q}$ .

Finally eq. (8) gives  $\omega_0$ .

Knowing  $\underline{Q}$  and  $\underline{\omega}$  the gravitomagnetic field  $\underline{Q}$  can be found from eq. (3).

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