

so (4): Simultaneous Equations for  $\underline{\omega}$  and  $\underline{\Phi}$  and for  $\underline{Q}$  and  $\omega_0$ .

Rotational Precession,  $\underline{\omega}$  and  $\underline{\Phi}$ .

There are two equations in two variables,  $\underline{\omega}$  and  $\underline{\Phi}$ :

$$\underline{g} = -\underline{\nabla} \underline{\Phi} + \underline{\omega} \underline{\Phi} = \gamma^3 \underline{\ddot{r}} = -M_1 G \frac{\underline{r}}{r^3} \quad - (1)$$

$$\text{and } \underline{\nabla} \cdot (-\underline{\nabla} \underline{\Phi} + \underline{\omega} \underline{\Phi}) = 4\pi G \rho_m \quad - (2)$$

In these equations,  $\gamma$ ,  $\underline{r}$  and  $\rho_m$  are known, so  $\underline{\Phi}$  and  $\underline{\omega}$  can be found.

Forward Precession,  $\underline{\omega}$  and  $\underline{\Phi}$

In this case:

$$\underline{g} = \underline{\ddot{r}} = \frac{M_1 G}{\gamma r^3} \left( \frac{\underline{\dot{r}} (\underline{\dot{r}} \cdot \underline{r})}{c^2} - \underline{r} \right) \quad - (3)$$
$$= -\underline{\nabla} \underline{\Phi} + \underline{\omega} \underline{\Phi}$$

$$\text{and } \underline{\nabla} \cdot (-\underline{\nabla} \underline{\Phi} + \underline{\omega} \underline{\Phi}) = 4\pi G \rho_m \quad - (4)$$

Again there are two equations in two unknowns,  $\underline{\omega}$  and  $\underline{\Phi}$ .

Rotational Precession,  $\underline{Q}$  and  $\omega_0$

There are two equations in two variables,  $\underline{Q}$  and  $\omega_0$ :

$$\underline{g} = -\frac{\partial \underline{Q}}{\partial t} - \underline{\omega}_0 \underline{Q} = \gamma^3 \underline{\ddot{r}} = -mG \frac{\underline{r}}{r^3} \quad - (5)$$

and

$$\underline{\nabla} \cdot \left( -\frac{\partial \underline{Q}}{\partial t} - \underline{\omega}_0 \underline{Q} \right) = 4\pi G \rho_m \quad - (6)$$

Forward Precession,  $\underline{Q}$  and  $\underline{\omega}_0$

I.L. case:

$$\underline{g} = \underline{\ddot{r}} = \frac{mG}{\gamma r^3} \left( \frac{\underline{\dot{r}} (\underline{\dot{r}} \cdot \underline{r})}{c^2} - \underline{r} \right) \quad - (7)$$

$$= -\frac{\partial \underline{Q}}{\partial t} - \underline{\omega}_0 \underline{Q}$$

and

$$\underline{\nabla} \cdot \left( -\frac{\partial \underline{Q}}{\partial t} - \underline{\omega}_0 \underline{Q} \right) = 4\pi G \rho_m \quad - (8)$$

Additionally, these are the equations of Note 380(3).

There is also the gravitational Faraday laws of induction:

which:

$$\underline{\nabla} \times \underline{g} + \frac{\partial \underline{\Omega}}{\partial t} = \underline{0} \quad - (9)$$

which:

$$\underline{g} = -\underline{\nabla} \Phi + \underline{\omega} \Phi = -\frac{\partial \underline{Q}}{\partial t} - \underline{\omega}_0 \underline{Q} \quad - (10)$$

and

$$\underline{\Omega} = \underline{\nabla} \times \underline{Q} - \underline{\omega} \times \underline{Q} \quad - (11)$$

Therefore:

$$\underline{\nabla} \times \left( -\frac{\partial \underline{a}}{\partial t} - \omega_0 \underline{a} \right) + \frac{\partial}{\partial t} \left( \underline{\nabla} \times \underline{a} - \underline{\omega} \times \underline{a} \right) = \underline{0} \quad - (12)$$

i.e.

$$\frac{\partial}{\partial t} (\underline{\omega} \times \underline{a}) = \underline{\nabla} \times (\omega_0 \underline{a}) \quad - (13)$$

Eq. (13) provides another equation to solve for six unknowns,  $\omega_x, \omega_y, \omega_z, a_x, a_y, a_z$ , plus  $\omega_0$ . In Eq. (13):

$$\underline{\nabla} \times (\omega_0 \underline{a}) = \omega_0 \underline{\nabla} \times \underline{a} + \underline{\nabla} \omega_0 \times \underline{a} \quad - (14)$$

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$$\frac{\partial}{\partial t} (\underline{\omega} \times \underline{a}) = \omega_0 \underline{\nabla} \times \underline{a} + \underline{\nabla} \omega_0 \times \underline{a} \quad - (15)$$

Comparing  $i, j$  and  $k$  components of eq. (15) gives three equations.

$$\omega_y a_z - \omega_z a_y = \omega_0 \left( \frac{\partial a_z}{\partial y} - \frac{\partial a_y}{\partial z} \right) + a_z \frac{\partial \omega_0}{\partial y} - a_y \frac{\partial \omega_0}{\partial z} \quad - (16)$$

$$\omega_z a_x - \omega_x a_z = \omega_0 \left( \frac{\partial a_x}{\partial z} - \frac{\partial a_z}{\partial x} \right) + a_x \frac{\partial \omega_0}{\partial z} - a_z \frac{\partial \omega_0}{\partial x} \quad - (17)$$

$$\omega_x a_y - \omega_y a_x = \omega_0 \left( \frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y} \right) + a_y \frac{\partial \omega_0}{\partial x} - a_x \frac{\partial \omega_0}{\partial y} \quad - (18)$$

) As in Note 380(3), let also the wave number satisfy equations:

$$\left(\frac{\partial}{\partial t} - \omega_y\right) Q_z = - \left(\frac{\partial}{\partial z} - \omega_z\right) Q_y \quad (19)$$

$$\left(\frac{\partial}{\partial z} - \omega_z\right) Q_x = - \left(\frac{\partial}{\partial x} - \omega_x\right) Q_z \quad (20)$$

$$\left(\frac{\partial}{\partial x} - \omega_x\right) Q_y = - \left(\frac{\partial}{\partial y} - \omega_y\right) Q_x \quad (21)$$

and for the laws:  $\underline{\nabla} \cdot \underline{\Omega} = 0 \quad (22)$

Let us write one more equation:

$$Q_x \left( \frac{\partial \omega_z}{\partial t} - \frac{\partial \omega_y}{\partial z} \right) + Q_y \left( \frac{\partial \omega_x}{\partial z} - \frac{\partial \omega_z}{\partial x} \right) + Q_z \left( \frac{\partial \omega_y}{\partial x} - \frac{\partial \omega_x}{\partial y} \right) \\ + \omega_x \left( \frac{\partial Q_z}{\partial t} - \frac{\partial Q_y}{\partial z} \right) + \omega_y \left( \frac{\partial Q_x}{\partial z} - \frac{\partial Q_z}{\partial x} \right) + \omega_z \left( \frac{\partial Q_y}{\partial x} - \frac{\partial Q_x}{\partial y} \right) \quad (23)$$

Eqs. (16) - (18), (19-21), and (23) are seven

equations in seven unknowns,  $\omega_x, \omega_y, \omega_z, Q_x, Q_y, Q_z$  and  $\omega_0$ . The system is exactly determined without other information.

Having found  $\omega_0, \underline{\omega}$  and  $\underline{Q}$ ,  $Q$  scalars

> potential  $\underline{\Phi}$  can be found from:

$$\underline{g} = -\underline{\nabla} \underline{\Phi} + \underline{\omega} \underline{\Phi} = -\frac{\partial Q}{\partial t} - \omega_0 \underline{Q} \quad (24)$$

so  $\underline{g}$  can be found unequivocally.

The general orbit may be found from eq. (24), using the method developed in UFT 378.

### Two Dimensional Orbits and the Newtonian limit

In two dimensions:

$$Q_z = \omega_z = 0 \quad (25)$$

and

$$\frac{\partial Q_y}{\partial z} = \frac{\partial Q_x}{\partial z} = \frac{\partial \omega_y}{\partial z} = \frac{\partial \omega_x}{\partial z} = 0 \quad (26)$$

so the problem reduces to:

$$\left( \frac{d}{dt} - \omega_x \right) Q_y = - \left( \frac{d}{dt} - \omega_y \right) Q_x \quad (27)$$

and

$$\omega_x Q_y - \omega_y Q_x = \omega_0 \left( \frac{\partial Q_y}{\partial x} - \frac{\partial Q_x}{\partial y} \right) + Q_y \frac{\partial \omega_0}{\partial x} - Q_x \frac{\partial \omega_0}{\partial y} \quad (28)$$

In the Newtonian limit:

$$\begin{aligned} \underline{g} &= -\frac{mg}{r^3} \underline{r} = -\underline{\nabla} \underline{\Phi} + \underline{\omega} \underline{\Phi} \\ &= -\frac{\partial Q}{\partial t} - \omega_0 \underline{Q} \quad (29) \end{aligned}$$

so:

$$g_x = \frac{-MGx}{(x^2 + y^2)^{3/2}} = -\frac{\partial Q_x}{\partial t} - \omega_0 Q_x \quad (30)$$

$$g_y = \frac{-MGy}{(x^2 + y^2)^{3/2}} = -\frac{\partial Q_y}{\partial t} - \omega_0 Q_y \quad (31)$$

Eqs. (27), (28), (30) and (31) are four equations in five unknowns,  $\omega_x$ ,  $\omega_y$ ,  $Q_x$ ,  $Q_y$  and  $\omega_0$ .

In the Newtonian limit:

$$\underline{g} = -\underline{\nabla} \underline{\Phi}_N \quad (32)$$

where

$$\underline{\Phi}_N = -\frac{MG}{r} = -\frac{MG}{(x^2 + y^2)^{1/2}} \quad (33)$$

In order to find a poisson equation we:

$$\underline{\nabla} \cdot \underline{g} = \underline{\nabla} \cdot \left( -\frac{\partial \underline{Q}}{\partial t} - \omega_0 \underline{Q} \right) = 4\pi G \rho / m \quad (34)$$

so

$$-\frac{\partial}{\partial t} (\underline{\nabla} \cdot \underline{Q}) - \omega_0 \underline{\nabla} \cdot \underline{Q} = 4\pi G \rho / m \quad (35)$$

which means that:

$$-\frac{\partial}{\partial t} \left( \frac{\partial Q_x}{\partial x} + \frac{\partial Q_y}{\partial y} \right) - \omega_0 \left( \frac{\partial Q_x}{\partial x} + \frac{\partial Q_y}{\partial y} \right) = 4\pi G \rho / m \quad (36)$$

So we do have five equations in five unknowns, eqs. (27), (28), (30), (31) and (36), in  $Q_x$ ,  $Q_y$ ,  $\omega_x$ ,  $\omega_y$  and  $\omega_0$ .  
 In the next note, the Ampere Maxwell law will be