

# 177(6) : Force Eigenvalue for Planar Rotation

In this case the quantum force equation is:

$$(\hat{H} - E) \left( \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \right) = F \psi \quad - (1)$$

where:

$$\hat{H} = -\frac{\hbar^2}{2m} \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \quad - (2)$$

In cylindrical coordinates:

$$\frac{\partial \psi}{\partial x} = \cos \phi \frac{\partial \psi}{\partial r} - \frac{\sin \phi}{r} \frac{\partial \psi}{\partial \phi} \quad - (3)$$

$$\frac{\partial \psi}{\partial y} = \sin \phi \frac{\partial \psi}{\partial r} + \frac{\cos \phi}{r} \frac{\partial \psi}{\partial \phi} \quad - (4)$$

and if  $r$  is constant:

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \phi^2} \quad - (5)$$

Therefore:

$$\frac{\partial^3 \psi}{\partial x^3} + \frac{\partial^3 \psi}{\partial y^3} = \frac{1}{r^3} (\cos \phi - \sin \phi) \frac{\partial^3 \psi}{\partial \phi^3} \quad - (6)$$

$$\frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} = \frac{1}{r} (\cos \phi - \sin \phi) \frac{\partial \psi}{\partial \phi} \quad - (7)$$

Thus:

$$\hat{H} \left( \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \right) = -\frac{\hbar^2}{2mr^3} (\cos \phi - \sin \phi) \frac{\partial^3 \psi}{\partial \phi^3} \quad - (8)$$

$$2) \text{ and } -E \left( \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \right) = -\frac{E}{r} (\cos \phi - \sin \phi) \frac{\partial \psi}{\partial \phi} \quad (9)$$

In general:

$$\psi = A \exp(im_J \phi) + B \exp(-im_J \phi) \quad (10)$$

$$E = \frac{m_J^2 \hbar^2}{2mr^2} \quad (11)$$

Therefore:

$$\frac{\partial \psi}{\partial \phi} = im_J (A e^{im_J \phi} - B e^{-im_J \phi}) \quad (12)$$

$$\frac{\partial^2 \psi}{\partial \phi^2} = -m_J^2 (A e^{im_J \phi} + B e^{-im_J \phi})$$

$$= -m_J^2 \psi \quad (13)$$

and

$$\frac{\partial^3 \psi}{\partial \phi^3} = -im_J^3 (A e^{im_J \phi} - B e^{-im_J \phi}) \quad (14)$$

so:

$$\begin{aligned} \hat{H} \left( \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \right) - E \left( \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} \right) &= F \psi \\ &= \frac{i \hbar^2 m_J^3}{2mr^2} (\cos \phi - \sin \phi) (A e^{im_J \phi} - B e^{-im_J \phi}) \\ &\quad - \frac{i \hbar^2 m_J^3}{2mr^2} (\cos \phi - \sin \phi) (A e^{im_J \phi} - B e^{-im_J \phi}) \\ &= 0 \end{aligned} \quad (15)$$

3) Therefore for all  $m_J$ :

$$\boxed{F = 0} \quad - (16)$$

This means that for circular or rotational motion in a plane there is no net force for all  $m_J$ .

This result is consistent with the assumption that  $r$  is constant, and checks that eq. (1) is correct. The next check is rotation on a sphere, where the wave functions are the spherical harmonics.

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