

## 207(6): Summary of Results

Consider the processing elliptical orbit:

$$r = \frac{d}{1 + e \cos(x\theta)} \quad - (1)$$

Then:  $\frac{dr}{d\theta} = \left(\frac{x e}{d}\right) r^2 \sin(x\theta) \quad - (2)$

In an orbit:

$$r = r(t), \quad \theta = \theta(t) \quad - (3)$$

because  $r$  and  $\theta$  are functions of time. Eq. (2) is the total derivative of  $r$  with respect to  $\theta$ .

Consider the function:

$$f = r^2 \left(\frac{d\theta}{dr}\right)^2 \quad - (4)$$

where eq. (3) applies. Then:

$$f = f(r(t), \theta(t)) \quad - (5)$$

This means that  $f$  is a function of  $r$  and  $\theta$ , and  $r$  is a function of  $t$  and  $\theta$  is a function of  $t$ . It follows that:

$$\boxed{\frac{df}{dt} = \frac{df}{dr} \frac{dr}{dt} + \frac{df}{d\theta} \frac{d\theta}{dt}} \quad - (6)$$

this is the chain rule.

2) Therefore:

$$\boxed{\frac{df}{dt} = \frac{dt}{d\theta} \left( \frac{df}{dt} - \frac{df}{dr} \frac{dr}{dt} \right)} \quad - (7)$$

Similarly:

$$\frac{df}{dr} = \frac{df}{dt} \frac{dt}{dr} + \frac{df}{d\theta} \frac{d\theta}{dr} \quad - (8)$$

So:

$$\boxed{\frac{df}{dt} = \frac{dr}{dt} \left( \frac{df}{dr} - \frac{df}{d\theta} \frac{d\theta}{dr} \right)} \quad - (9)$$

The connections are:

$$\Gamma^1_{01} = \frac{1}{2c g_{11}} \frac{dg_{11}}{dt} \quad - (10)$$

$$\Gamma^1_{21} = \frac{1}{2 g_{11}} \frac{dg_{11}}{d\theta} \quad - (11)$$

where  $g_{11} = - (1 + f) \quad - (12)$

Therefore:

$$\Gamma'_{01} = -\frac{1}{2c(1+f)} \frac{df}{dt} \quad - (13)$$

$$\Gamma'_{21} = -\frac{1}{2r(1+f)} \frac{df}{d\theta} \quad - (14)$$

i.e.

$$\Gamma'_{01} = -\frac{1}{2c(1+f)} \frac{dr}{dt} \left( \frac{df}{dr} - \frac{df}{d\theta} \frac{d\theta}{dr} \right) \quad - (15)$$

$$\Gamma'_{21} = -\frac{1}{2r(1+f)} \frac{dt}{d\theta} \left( \frac{df}{dr} - \frac{df}{d\theta} \frac{dr}{dt} \right) \quad - (16)$$

- 1) Note carefully that the partial derivatives  $df/d\theta$  and  $df/dt$  are defined by the chain rule, and contain time derivatives.
- 2) The total derivatives  $df/d\theta$  and  $df/dt$  are different in structure. Only the total derivatives can be evaluated from eq. (4), i.e. only  $df/dr$  and  $df/d\theta$ .

4) The code is formally correct in terms of  $f$ , but to go any further it is necessary to know the various quantities in eqs. (15) and (16).  
 Here are three chain rules:

$$\frac{df}{dt} = \frac{df}{dr} \frac{dr}{dt} + \frac{df}{dt} \frac{dt}{dt} \quad - (17)$$

$$\frac{df}{dr} = \frac{df}{dt} \frac{dt}{dr} + \frac{df}{dr} \frac{dr}{dr} \quad - (18)$$

$$\frac{df}{dt} = \frac{df}{dr} \frac{dr}{dt} + \frac{df}{dt} \frac{dt}{dr} \quad - (19)$$

The metric definition is:

$$ds^2 = g_{\mu\nu} dx^\mu dx^\nu = c^2 dt^2 - dr^2 - r^2 d\theta^2 \quad - (20)$$

with  $g_{00} = 1, g_{11} = -1, g_{22} = -1$   
 $dx^0 = c dt, dx^1 = dr, dx^2 = r d\theta$  - (21)

The constraint is:

$$dx^2 = \left( r \frac{d\theta}{dr} \right) dr \quad - (22)$$

line element

the metric is:

5)

$$ds^2 = g_{00} dx^0 dx^0 + g_{11} dx^1 dx^1 + g_{22} dx^2 dx^2$$

$$= c^2 dt^2 - dr^2 - r^2 \left( \frac{d\theta}{dr} \right)^2 dr^2 \quad - (23)$$

i.e.  $dx^2 = \frac{d\theta}{dr} r dr = r d\theta \quad - (24)$

$$dx^1 = dr \quad - (25)$$

so  $dx^2 = \left( r \frac{d\theta}{dr} \right) dx^1 \quad - (26)$

Therefore:

$$ds^2 = g_{00} dx^0 dx^0 + g_{11} dx^1 dx^1 + g_{22} \left( r \frac{d\theta}{dr} \right)^2 dx^1 dx^1 \quad - (27)$$

The number of coordinates to be reduced from three to two.

This can be interpreted in two ways.

1) The spacetime remains flat, i.e.

$$g_{00} = 1, g_{11} = -1, g_{22} = -1 \quad - (28)$$

2) The spacetime becomes non-Minkowski in the sense that:

$$ds^2 = g_{00} dx^0 dx^0 + g'_{11} dx^1 dx^1 \quad - (29)$$

where:

$$g'_{11} = g_{11} + \left( r \frac{d\theta}{dx} \right)^2 g_{22} \quad - (30)$$

The metric for case (2) is:

$$g_{\mu\nu} = \begin{bmatrix} 1 & 0 \\ 0 & -(1+f) \end{bmatrix} \quad - (31)$$

The metric for case (1) is:

$$g_{\mu\nu} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \quad - (32)$$

So there is only one convention, eq. (15).