

## 207(a): Development of the Identity Equations

The two identity equations are:

$$D_0 T'_{01} = R^1_{001} \quad - (1)$$

and  $D_1 T'_{10} = R^1_{110} \quad - (2)$

These become:

$$6(1+f) \frac{\partial}{\partial t} \left( \frac{df}{\partial t} \right) = 5 \left( \frac{df}{\partial t} \right)^2 \quad - (3)$$

and  $(1+f) \frac{\partial}{\partial r} \left( \frac{df}{\partial t} \right) = \frac{df}{\partial r} \frac{df}{\partial t} \quad - (4)$

These must be solved simultaneously, so if:

$$x = \frac{df}{\partial t}, \quad y = \frac{df}{\partial r} \quad - (5)$$

$$(1+f) \frac{dx}{\partial r} = xy \quad - (6)$$

$$6(1+f) \frac{dx}{\partial t} = 5x^2 \quad - (7)$$

Divide (7) by (6):

$$6 \frac{dx}{\partial t} \frac{\partial r}{\partial x} = 5 \frac{x}{y} \quad - (8)$$

i.e.  $\boxed{6y \frac{\partial r}{\partial t} = 5x} \quad - (9)$

The equation of motion or field equation is:

$$6 \frac{\partial x}{\partial t} = 5 \frac{\partial x}{\partial t} - (10)$$

So:

$$\boxed{\frac{\partial x}{\partial t} = 0} - (11)$$

This means that:

$$\frac{d}{dt} \left( \frac{df}{d\theta} \right) = 0 - (12)$$

where

$$\frac{df}{d\theta} = \frac{1}{2} \omega \frac{df}{d\theta} - (13)$$

so

$$\frac{d}{dt} \left( \omega \frac{df}{d\theta} \right) = 0, - (14)$$

or

$$\boxed{\frac{\partial \omega}{\partial t} \frac{df}{d\theta} + \omega \frac{d}{dt} \left( \frac{df}{d\theta} \right) = 0} - (15)$$

using the Leibniz rule.

It is seen that eq. (15) is an equation of motion, giving:

$$\boxed{\frac{\partial \omega}{\partial t} = - \frac{\omega}{x_1} \frac{\partial x_1}{\partial t} - (16)}$$

where

$$x_1 = \frac{df}{d\theta}.$$

3) The field equation or equation of motion is given by:

$$\frac{d\omega}{dt} = - \frac{\omega \frac{d}{dt} \left( \frac{df}{d\theta} \right)}{\left( \frac{df}{d\theta} \right)} \quad - (17)$$

where

$$f = r^2 \left( \frac{d\theta}{dr} \right)^2 \quad - (18)$$

This is true for all orbits.