

219(9): Simplest Solution of the Three Particle Problem

Consider two planets of masses m_1 and m_2 orbiting. The sum of mass M is a plane. The centre of mass of m_1 and m_2 is determined by:

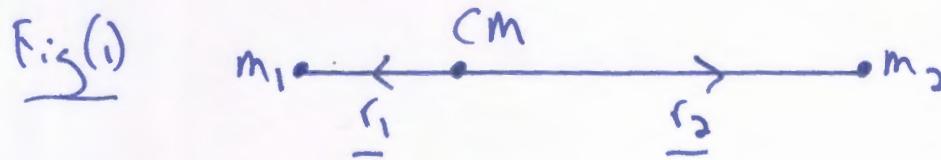
$$m_1 \underline{r}_1 + m_2 \underline{r}_2 = \underline{0} \quad - (1)$$

The two masses are separated by:

$$\underline{r} = \underline{r}_1 - \underline{r}_2 \quad - (2)$$

and the Lagrangian for m_1 and m_2 is:

$$L = \frac{1}{2} m_1 |\dot{\underline{r}}_1|^2 + \frac{1}{2} m_2 |\dot{\underline{r}}_2|^2 - u(\underline{r}) \quad - (3)$$



From eqs. (1) and (2):

$$\underline{r}_1 = \frac{m_2}{m_1 + m_2} \underline{r}, \quad \underline{r}_2 = -\frac{m_1}{m_1 + m_2} \underline{r} \quad - (4)$$

From eqs. (3) and (4):

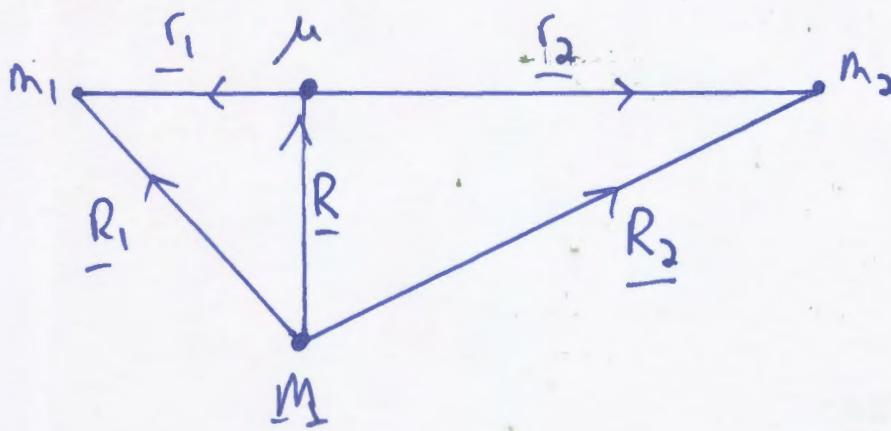
$$L = \frac{1}{2} \mu |\dot{\underline{r}}|^2 - u(\underline{r}) \quad - (5)$$

where $\mu = \frac{m_1 m_2}{m_1 + m_2} \quad - (6)$

Explain why Lagrangian (5) describes the motion of \underline{r} reduced mass μ and the distance \underline{r} . Between m_1 and m_2 .

2)

Fig.(2)



Fig(2)

Similarly the motion of m around M is described

$$\text{by: } L_1 = \frac{1}{2} \mu_1 |R| \dot{\theta}^2 - u(R) \quad (7)$$

$$\text{where } \mu_1 = \frac{\mu M}{\mu + M}. \quad (8)$$

The orbit of m around M is:

$$R = \frac{d}{1 + \epsilon \cos(\varphi \theta)}, \quad (9)$$

with conserved angular momentum:

$$L = \mu_1 R^2 \frac{d\theta}{dt}. \quad (10)$$

$$\text{Here: } d = \frac{L^2}{\mu_1 k}, \quad \epsilon = \left(1 + \frac{2EL^2}{\mu_1 k^2} \right)^{1/2}, \quad (11)$$

$$k = \frac{\mu M G}{4\pi^2}$$

The distances R_1 and R_2 between planets m_1 and m_2 are given by:

$$\underline{R}_1 = \underline{R} + \underline{r}_1 \quad - (12)$$

$$\underline{R}_2 = \underline{R} + \underline{r}_2 \quad - (13)$$

i.e.

$$\underline{R}_1 = \underline{R} + \left(\frac{m_2}{m_1 + m_2} \right) \underline{r} \quad - (14)$$

$$\underline{R}_2 = \underline{R} - \left(\frac{m_1}{m_1 + m_2} \right) \underline{r} \quad - (15)$$

Result of r is given by:

$$r = \frac{d_1}{1 + E_1 \cos(\chi_1 \theta)} \quad - (16)$$

with angular momentum:

$$L_1 = \mu r^2 \frac{d\theta}{dt}, \quad - (17)$$

$$d_1 = \frac{L_1^2}{\mu k_1}, \quad E_1 = \left(1 + \frac{2E_1 L_1^2}{\mu k_1^2} \right) \quad - (18)$$

$$k_1 = m_1 m_2 b$$

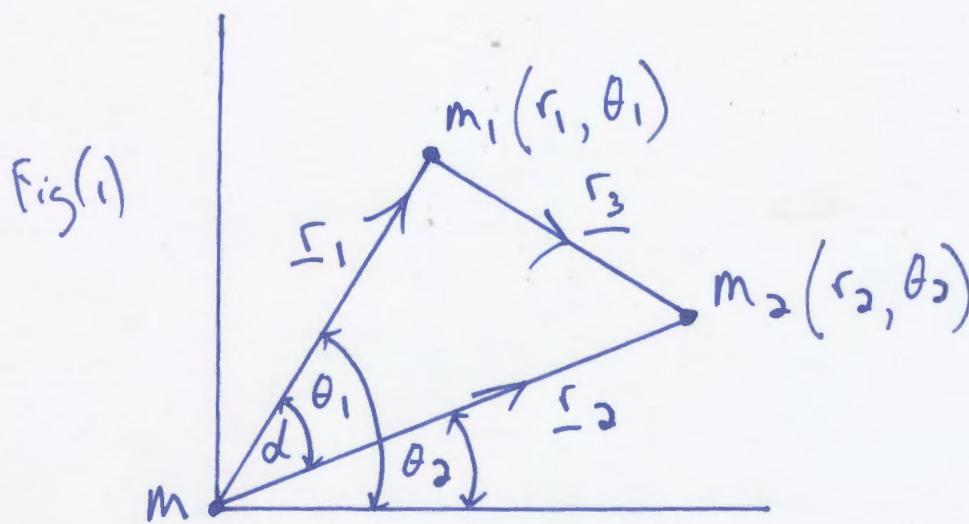
From eqs. (14) and (15):

$$\boxed{\underline{R}_1 - \underline{R}_2 = \left(\frac{m_2 - m_1}{m_1 + m_2} \right) \underline{r}} \quad - (19)$$

so: $r = \left(\frac{m_1 + m_2}{m_2 - m_1} \right) | \underline{R}_1 - \underline{R}_2 | \quad - (20)$

219(10): Alignment of Two Planets w/ the Sun.

In general the geometry is sketched in Fig. (1).



It is described by:

$$d = \theta_1 - \theta_2, \quad -(1)$$

$$\underline{r}_1 = \underline{r}_2 - \underline{r}_3. \quad -(2)$$

$$\underline{r}_1^2 = (\underline{r}_2 - \underline{r}_3) \cdot (\underline{r}_2 - \underline{r}_3) \quad -(3)$$

So:
$$\begin{aligned} \underline{r}_1^2 &= (\underline{r}_2 - \underline{r}_3) \cdot (\underline{r}_2 - \underline{r}_3) \\ &= \underline{r}_2^2 + \underline{r}_3^2 - 2 \underline{r}_2 \cdot \underline{r}_3 \cos(\theta_1 - \theta_2). \end{aligned}$$

Here:
$$\underline{r}_1 = \frac{\underline{d}_1}{1 + \epsilon_1 \cos(x_1 \theta_1)}, \quad \underline{r}_2 = \frac{\underline{d}_2}{1 + \epsilon_2 \cos(x_2 \theta_2)} \quad -(4)$$

From eqn (3):

$$\underline{r}_3^2 + A \underline{r}_3 + B = 0 \quad -(5)$$

where:

$$2) \quad A = -2r_2 \cos(\theta_1 - \theta_2), \quad B = r_2^2 - r_1^2 \quad -(6)$$

so $r_3 = \frac{1}{2} \left(-A \pm \sqrt{A^2 - 4B} \right)^{1/2} \quad -(7)$

$$= \frac{1}{2} \left(2r_2 \cos(\theta_1 - \theta_2) \pm \sqrt{4r_2^2 \cos^2(\theta_1 - \theta_2) - 4(r_2^2 - r_1^2)} \right)^{1/2}$$

i.e. $r_3 = r_2 \cos(\theta_1 - \theta_2) \pm \sqrt{r_1^2 - r_2^2 \left(1 - \cos^2(\theta_1 - \theta_2) \right)} \quad -(8)$

If m_1, m_2 and m_3 are in alignment:

$$\theta_1 = \theta_2 \quad -(9)$$

so
$$r_3 = \frac{d_2}{1 + F_1 \cos(x_1 \theta_1)} - \frac{d_1}{1 + F_2 \cos(x_2 \theta_2)} \quad -(10)$$

If there were no interaction between m_1 and m_2 , then r_3 is given by eq. (8). However, in the three particle problem:

$$r_3 = \frac{d_3}{1 + F_3 \cos(x_3 \theta_3)} \quad -(11)$$

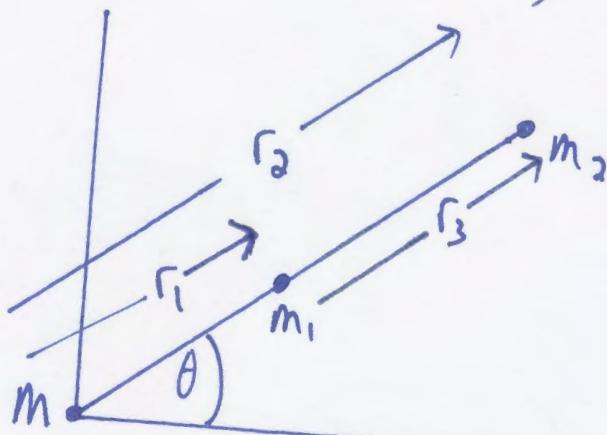
hence from eqs. (3) and (11) it is possible to derive a relation between θ_1, θ_2 and θ_3 .

In the case of alignment eq. (10) can be written as:

$$\theta_1 = \theta_2 = \theta \rightarrow (12)$$

so

$$r_3 = \frac{d_2}{1 + \epsilon_1 \cos(x_1 \theta)} - \frac{d_1}{1 + \epsilon_2 \cos(x_2 \theta)} \quad - (13)$$



Fig(2)

If there is no gravitational interaction between m_1 and m_2 then r_3 can be plotted against θ as in eq. (13). If there is gravitational interaction then:

$$r_3 = \frac{d_3}{1 + \epsilon_3 \cos(x_3 \theta_3)} \quad - (14)$$

$$\text{so:} \quad \frac{d_3}{1 + \epsilon_3 \cos(x_3 \theta_3)} = \frac{d_2}{1 + \epsilon_1 \cos(x_1 \theta)} - \frac{d_1}{1 + \epsilon_2 \cos(x_2 \theta)} \quad - (15)$$

$$\frac{d_3}{1 + \epsilon_3 \cos(x_3 \theta_3)} = \frac{d_2}{1 + \epsilon_1 \cos(x_1 \theta)} - \frac{d_1}{1 + \epsilon_2 \cos(x_2 \theta)}$$

and θ_3 can be plotted against θ .

4) In ob. Newton's limit:

$$\frac{d_3}{1 + \epsilon_3 \cos \theta_3} = \frac{d_2}{1 + \epsilon_1 \cos \theta} - \frac{d_1}{1 + \epsilon_2 \cos \theta} \quad -(16)$$
$$= \frac{d_2(1 + \epsilon_2 \cos \theta) - d_1(1 + \epsilon_1 \cos \theta)}{(1 + \epsilon_1 \cos \theta)(1 + \epsilon_2 \cos \theta)}$$

So:

$$1 + \epsilon_3 \cos \theta_3 = \frac{d_3(1 + \epsilon_1 \cos \theta)(1 + \epsilon_2 \cos \theta)}{d_2(1 + \epsilon_2 \cos \theta) - d_1(1 + \epsilon_1 \cos \theta)} \quad -(17)$$

$$\theta_3 = \cos^{-1} \left[\frac{1}{\epsilon_3} \left(\frac{d_3(1 + \epsilon_1 \cos \theta)(1 + \epsilon_2 \cos \theta)}{d_2(1 + \epsilon_2 \cos \theta) - d_1(1 + \epsilon_1 \cos \theta)} \right) - 1 \right] \quad -(18)$$