

220(8): Summary of Theory for 2 Two Particle and N Particle Problems.

In 2 particle problem:

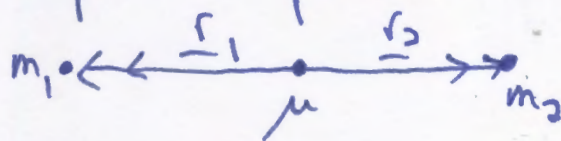


Fig (1)

The Lagrangian is:

$$L = \frac{1}{2} m_1 |\dot{\underline{r}}_1|^2 + \frac{1}{2} m_2 |\dot{\underline{r}}_2|^2 - u(R) \quad - (1)$$

where

$$\underline{R} = \underline{r}_1 - \underline{r}_2 \quad - (2)$$

The centre of mass of m_1 and m_2 is defined by:

$$m_1 \underline{r}_1 + m_2 \underline{r}_2 = \underline{0} \quad - (3)$$

Therefore:

$$\underline{r}_1 = \frac{m_2}{m_1 + m_2} \underline{R}, \quad \underline{r}_2 = -\frac{m_1}{m_1 + m_2} \underline{R} \quad - (4)$$

Therefore:

$$L = \frac{1}{2} \mu |\dot{\underline{R}}|^2 - u(R) \quad - (5)$$

where

$$\mu = \frac{m_1 m_2}{m_1 + m_2} \quad - (6)$$

In plane cylindrical coordinates:

$$\begin{aligned} \dot{\underline{R}} &= \dot{R} \underline{e}_r + R \dot{\underline{e}}_r \quad - (7) \\ &= \dot{R} \underline{e}_r + R \dot{\theta} \underline{e}_\theta \end{aligned}$$

Here:

$$\underline{R} = X \underline{i} + Y \underline{j} = R \cos \theta \underline{i} + R \sin \theta \underline{j} \quad - (8)$$

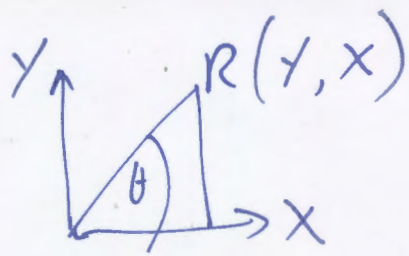
Here:

$$\underline{e}_r = \underline{i} \cos \theta + \underline{j} \sin \theta$$

$$\underline{e}_\theta = -\underline{i} \sin \theta + \underline{j} \cos \theta$$

$$\underline{i} = \underline{e}_r \cos \theta - \underline{e}_\theta \sin \theta$$

$$\underline{j} = \underline{e}_r \sin \theta + \underline{e}_\theta \cos \theta$$



So:

$$\underline{R} = X \underline{i} + Y \underline{j}$$

$$= R \cos \theta (\underline{e}_r \cos \theta - \underline{e}_\theta \sin \theta) + R \sin \theta (\underline{e}_r \sin \theta + \underline{e}_\theta \cos \theta)$$

$$= R \underline{e}_r (\cos^2 \theta + \sin^2 \theta) - (a)$$

$$= R \underline{e}_r$$

Re time derivative of \underline{e}_r is:

$$\dot{\underline{e}}_r = \frac{d\underline{e}_r}{dt} = \frac{d}{dt} (\underline{i} \cos \theta(t) + \underline{j} \sin \theta(t)) - (10)$$

so:

$$\dot{\underline{e}}_r = \dot{\theta} \underline{e}_\theta - (11)$$

$$\dot{\underline{e}}_\theta = -\dot{\theta} \underline{e}_r - (12)$$

Therefore:

$$\mathcal{L} = \frac{1}{2} \mu (\dot{R}^2 + R^2 \dot{\theta}^2) - u(R) - (13)$$

Re Euler Lagrange equation is:

$$\frac{\partial \mathcal{L}}{\partial q_j} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}_j}, \quad - (14)$$

$j = 1, 2, \dots, s$

3) and the Lagrangian is:

$$L = T(q_j, \dot{q}_j, t) - U(q_j, t) \quad (15)$$

Here q_j are the generalized coordinates, a set of quantities that specify completely the state of the system, with number of degrees of freedom S .

For the Lagrangian (13):

$$\frac{\partial L}{\partial r} = \frac{d}{dt} \frac{\partial L}{\partial \dot{r}} \quad (16)$$

$$\frac{\partial L}{\partial \theta} = \frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} \quad (17)$$

These reduce to:

$$\frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} = - \frac{\mu r^2}{L^2} F(r), \quad (18)$$

where

$$F(r) = - \frac{\partial U(r)}{\partial r} \quad (19)$$

and

$$L = \mu r^2 \frac{d\theta}{dt} \quad (20)$$

For a Hooke Newton potential:

$$U(r) = - m_1 m_2 G / r \quad (21)$$

the orbit is a static ellipse:

$$4) \quad r = \frac{d}{1 + e \cos \theta} \quad - (22)$$

and note generally the static conical section. Here:

$$L^2 = d \mu k \quad - (23)$$

where $k = m_1 m_2 G \quad - (24)$

and $d = a(1 - e^2) \quad - (25)$

where a is the semi major axis.

The time taken for a mass to sweep out an angle θ is:

$$\tau = \frac{d^{3/2}}{m_1 m_2 G} f(\theta) \quad - (26)$$

where:

$$f(\theta) = \int \frac{1}{(1 + \cos \theta)^2} d\theta \quad - (27)$$

$$= \frac{2}{(1 - e^2)^{3/2}} \tan^{-1} \left((1 - e^2)^{1/2} \tan \frac{\theta}{2} \right) - \frac{e \sin \theta}{(1 - e^2)(1 + e \cos \theta)}$$

The area of the ellipse is:

$$A = \frac{1}{2} \int_0^{2\pi} \frac{d\theta}{(1 + \cos \theta)^2} = \pi ab. \quad - (28)$$

In time τ , the angle has swept out 2π radians, covering the entire area πab of the static ellipse. In a time t , an area $(\pi ab / \tau) t$ is swept out. So:

$$\frac{\pi ab}{\tau} t = \int dA = \frac{1}{2} \int_0^\theta r^2 d\theta. \quad - (29)$$

Here

$$ab = \frac{d^2}{(1-e^2)^{3/2}} \quad - (30)$$

so:

$$t = \frac{\tau}{2\pi} \left[2 \tan^{-1} \left(\left(\frac{1-e}{1+e} \right)^{1/2} \tan \frac{\theta}{2} \right) - \frac{e(1-e^2)^{1/2} \sin \theta}{1+e \cos \theta} \right] \quad - (31)$$

This is the time taken for θ to change from zero to θ . It is expressed in terms of the fundamental observables of the orbit: τ and e , and can be measured with great accuracy in modern astronomy. Using computer algebra eq. (31) can be inverted to give:

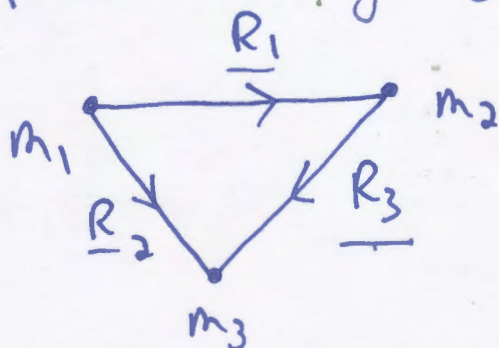
$$\theta = f(t) \quad - (32)$$

to machine precision. Approximately:

$$\begin{aligned} \theta(t) = & \frac{2\pi t}{\tau} + 2e \sin \frac{2\pi t}{\tau} + \frac{5}{4} e^2 \sin \frac{4\pi t}{\tau} \\ & + \frac{1}{12} e^3 \left(13 \sin \frac{6\pi t}{\tau} - 3 \sin \frac{2\pi t}{\tau} \right) \\ & + \dots \quad - (33) \end{aligned}$$

6) Three Particle Problem

This is sketched in Fig (2) :



so:

$$\underline{R_2} = \underline{R_1} + \underline{R_3} \quad - (34)$$

Here:

$$\underline{R_i} = R_i \underline{e_r}, \quad - (35)$$

$i = 1, 2, 3$

so

$$R_2 = R_1 + R_3 \quad - (36)$$

Here:

$$R_1 = |\underline{r_1} - \underline{r_2}| \quad - (37)$$

$$R_2 = |\underline{r_1} - \underline{r_3}| \quad - (38)$$

$$R_3 = |\underline{r_2} - \underline{r_3}| \quad - (39)$$

and

$$m_1 \underline{r_1} + m_2 \underline{r_2} = \underline{0} \quad - (40)$$

$$m_1 \underline{r_1} + m_3 \underline{r_3} = \underline{0} \quad - (41)$$

$$m_2 \underline{r_2} + m_3 \underline{r_3} = \underline{0} \quad - (42)$$

define the centre of mass.

The three particle problem means that m_1 interacts simultaneously w/ m_2 and m_3 and so on. m_2 and m_3 interact w/ m_1 and so on.

7) The three particle Lagrangian is:

$$L = \frac{1}{2} (m_1 |\dot{\underline{r}}_1|^2 + m_2 |\dot{\underline{r}}_2|^2 + m_3 |\dot{\underline{r}}_3|^2) - \frac{m_1 m_2 \Gamma}{|\underline{r}_1 - \underline{r}_2|} - \frac{m_1 m_3 \Gamma}{|\underline{r}_1 - \underline{r}_3|} - \frac{m_2 m_3 \Gamma}{|\underline{r}_2 - \underline{r}_3|} \quad (43)$$

and is factorized as follows:

$$L_1 = \frac{1}{2} (m_1 |\dot{\underline{r}}_1|^2 + m_2 |\dot{\underline{r}}_2|^2) - \frac{2m_1 m_2 \Gamma}{|\underline{r}_1 - \underline{r}_2|} \quad (44)$$

$$L_2 = \frac{1}{2} (m_1 |\dot{\underline{r}}_1|^2 + m_3 |\dot{\underline{r}}_3|^2) - \frac{2m_1 m_3 \Gamma}{|\underline{r}_1 - \underline{r}_3|} \quad (45)$$

$$L_3 = \frac{1}{2} (m_2 |\dot{\underline{r}}_2|^2 + m_3 |\dot{\underline{r}}_3|^2) - \frac{2m_2 m_3 \Gamma}{|\underline{r}_2 - \underline{r}_3|} \quad (46)$$

Each one of these has the same format as eq. (1). Therefore the Lagrangians (44) to (46) generate three inter-related elliptical orbits. Following the method of eq. (1) and following equations, the factorized Lagrangians can be written as:

$$L_1 = \frac{1}{2} \mu_1 |\dot{\underline{R}}_1|^2 - u(R_1) \quad (47)$$

$$L_2 = \frac{1}{2} \mu_2 |\dot{\underline{R}}_2|^2 - u(R_2) \quad (48)$$

$$L_3 = \frac{1}{2} \mu_3 |\dot{\underline{R}}_3|^2 - u(R_3) \quad (49)$$

in the format of eq. (5). Here:

$$\mu_1 = \frac{m_1 m_2}{m_1 + m_2}, \quad \mu_2 = \frac{m_1 m_3}{m_1 + m_3}, \quad \mu_3 = \frac{m_2 m_3}{m_2 + m_3} \quad (50)$$

$$U_1 = -\frac{2m_1 m_2 \Gamma}{R_1}, \quad U_2 = -\frac{2m_1 m_3 \Gamma}{R_2}, \quad U_3 = -\frac{2m_2 m_3 \Gamma}{R_3}.$$

We define:

$$k_1 = 2m_1 m_2 \Gamma, \quad k_2 = 2m_1 m_3 \Gamma, \quad k_3 = 2m_2 m_3 \Gamma. \quad (51)$$

In plane cylindrical coordinates, eqs. (47) to (49)

are:

$$L_1 = \frac{1}{2} \mu_1 (\dot{R}_1^2 + R_1^2 \dot{\theta}_1^2) - u(R_1) \quad (54)$$

$$L_2 = \frac{1}{2} \mu_2 (\dot{R}_2^2 + R_2^2 \dot{\theta}_2^2) - u(R_2) \quad (55)$$

$$L_3 = \frac{1}{2} \mu_3 (\dot{R}_3^2 + R_3^2 \dot{\theta}_3^2) - u(R_3) \quad (56)$$

$$L_3 = \frac{1}{2} \mu_3 (\dot{R}_3^2 + R_3^2 \dot{\theta}_3^2) - u(R_3) \quad (56)$$

Each Lagrangian is governed by Euler Lagrange equations of type (14). So:

$$\frac{\partial L_i}{\partial R_i} = \frac{d}{dt} \frac{\partial L_i}{\partial \dot{R}_i}, \quad (57)$$

$$\frac{\partial L_i}{\partial \theta_i} = \frac{d}{dt} \frac{\partial L_i}{\partial \dot{\theta}_i}, \quad (58)$$

$i = 1, 2, 3$. So there are three equations of type (18):

$$\frac{d^2}{d\theta_i^2} \left(\frac{1}{R_i} \right) + \frac{1}{R_i} = - \frac{\mu_i R_i^2 F_i(R_i)}{L_i^2} \quad (59)$$

$i = 1, 2, 3$

Here:

$$F_1 = -\frac{2m_1 m_2 G}{R_1^2}, F_2 = -\frac{2m_1 m_3 G}{R_2^2}, F_3 = -\frac{2m_2 m_3 G}{R_3^2}$$

$$L_1^2 = d_1 \mu_1 k_1, L_2^2 = d_2 \mu_2 k_2, \quad - (60)$$

$$L_3^2 = d_3 \mu_3 k_3. \quad - (61)$$

So there are three inter-related orbits:

$$R_i = \frac{d_i}{1 + \epsilon_i \cos \theta_i}, \quad - (62)$$

$$i = 1, 2, 3.$$

From eqs. (36) and (62):

$$\frac{d_2}{1 + \epsilon_2 \cos \theta_2} = \frac{d_1}{1 + \epsilon_1 \cos \theta_1} + \frac{d_3}{1 + \epsilon_3 \cos \theta_3} \quad - (63)$$

If for example m_1 is the sun, m_2 is the earth and m_3 is Mars, then the orbit of Mars about the earth is given by:

$$\frac{d_3}{1 + \epsilon_3 \cos \theta_3} = \frac{d_2}{1 + \epsilon_2 \cos \theta_2} - \frac{d_1}{1 + \epsilon_1 \cos \theta_1}. \quad - (64)$$

The orbit of the earth about the sun is given by:

$$\frac{d_1}{1 + \epsilon_1 \cos \theta_1} = \frac{d_2}{1 + \epsilon_2 \cos \theta_2} - \frac{d_3}{1 + \epsilon_3 \cos \theta_3} \quad - (65)$$

The orbit of Mer about the sun is given by eq. (63).

In order to evaluate orbital elapsed time we get result:

$$\int \frac{d\theta}{(1 + \epsilon \cos \theta)^2} = \frac{\epsilon \sin \theta}{(\epsilon^2 - 1)(1 + \epsilon \cos \theta)} - \left(\frac{\epsilon}{1 - \epsilon^2} \right) \int \frac{d\theta}{1 + \epsilon \cos \theta} \quad - (66)$$

From eq. (65):

$$\begin{aligned} \int \frac{d_1}{1 + \epsilon_1 \cos \theta_1} d\theta_1 &= \int \frac{d_1}{1 + \epsilon_1 \cos \theta} d\theta \\ &= \int \frac{d_2}{1 + \epsilon_2 \cos \theta_2} d\theta_2 - \int \frac{d_3}{1 + \epsilon_3 \cos \theta_3} d\theta_3 \end{aligned} \quad - (67)$$

So:

$$\int \frac{d_1}{(1 + \epsilon_1 \cos \theta)^2} d\theta = \frac{d_1 \epsilon_1 \sin \theta}{(\epsilon_1^2 - 1)(1 + \epsilon_1 \cos \theta)} - \frac{\epsilon_1}{1 - \epsilon_1^2} \left(\int \frac{d_2}{1 + \epsilon_2 \cos \theta_2} d\theta_2 - \int \frac{d_3}{1 + \epsilon_3 \cos \theta_3} d\theta_3 \right) \quad - (68)$$

It is seen that the orbital elapsed time of the earth about the sun is affected by the other two orbits. The next note will evaluate this.