

262(8): Comparison of Theories of Orbital Precession

For any planar orbit:

$$\underline{F}(r) = -\frac{\underline{L}^2}{mr^3} \left(\frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} \right) \underline{e}_r \quad -(1)$$

Theory $\frac{1}{1}$

$$\text{If } \underline{F}(r) = \left(-\frac{mMg}{r^2} - \frac{3GM\underline{L}^2}{mc^2 r^4} \right) \underline{e}_r \quad -(2)$$

then $\omega = \omega_0 \left(1 + \frac{6Mg}{\underline{L}c^2} \right) \quad -(3)$
 of Newtonian

here ω_0 is the angular velocity of the orbit defined by: $\underline{F}(r) = -\frac{mMg}{r^2} \underline{e}_r \quad -(4)$

i.e. $\omega_0 = \frac{\underline{L}}{mr^2} \quad -(5)$

and $d\theta = \left(\frac{3Mg}{ac^2(1-e^2)} \right) \theta \quad -(6)$

The force law (2) is due to the Coriolis effect
 spin correction (3) . At the orbital turning
 point $\frac{d^2r}{dt^2} = 0 \quad -(7)$

2) then

$$r = \alpha - r_0 = \frac{\alpha}{1 + \epsilon \cos \theta} \quad -(8)$$

where

$$r_0 = \frac{3M\bar{v}}{c^2}. \quad -(9)$$

Theory 2

If:

$$\underline{F}(r) = (x^2 - 1) \frac{L^2}{mr^3} - \frac{x^2 L^2}{\alpha mr^3} \quad -(10)$$

then:

$$\Delta \theta = x\theta \quad -(11)$$

and

$$r = \frac{d}{1 + \epsilon \cos(x\theta)} \quad -(12)$$

At the orbital turning point:

$$r = \alpha. \quad -(13)$$

So Theory 2 changes the angle from θ to $x\theta$, but does not change the turning point of the Newtonian orbit, while Theory 1 leaves the angle θ same but changes the turning point:

$$d \rightarrow d - r_0. \quad -(14)$$

3) If the two laws have the same effect then:

$$x = \frac{3M\bar{G}}{ac^2(1-e^2)} - (15)$$

So two different force laws (2) and (10) produce the same observed precession. Therefore the precessional method cannot distinguish between the two force laws, proving that the force law (2) is not unique.

In the Newton theory let:

$$r \rightarrow r + r_0 - (16)$$

so

$$\begin{aligned} F &= -\frac{mM\bar{G}}{r^2} \rightarrow -\frac{mM\bar{G}}{(r+r_0)^2} \\ &= -\frac{mM\bar{G}}{r^2} \left(1+\frac{r_0}{r}\right)^{-2} = -\frac{mM\bar{G}}{r^2} \left(1-2\frac{r_0}{r}\right) \end{aligned} - (17)$$

if $r_0 \ll r$. - (18)

so

$$F = -\frac{mM\bar{G}}{r^2} + \frac{2mM\bar{G}r_0}{r^3} - (18)$$

Now compare eqs. (10) and (18) with

$$4) \quad x \approx 1, \quad d = \frac{L^2}{m^2 M G} - (19)$$

to find:

$$x^2 = 1 + 2 \frac{r_0}{d} - (20)$$

to an excellent approximation If:

$$r_0 \ll d - (21)$$

then:

$$x = \left(1 + 2 \frac{r_0}{d}\right)^{1/2} = 1 + \frac{r_0}{d} - (22)$$

$$\text{So if } x = 1 + \frac{r_0}{d} - (23)$$

then

$$r \rightarrow r + r_0 - (24)$$

It follows that:

$$r + r_0 = \frac{d}{1 + \epsilon \cos \theta} - (25)$$

is equivalent to:

$$r = \frac{d}{1 + \epsilon \cos \left(\left(1 + \frac{r_0}{d}\right) \theta \right)} - (26)$$

At the turning point:

$$r + r_0 = d - (27)$$

so

$$r = d - r_0 - (28)$$

5) However, eq. (28) is the result of eq. (2),
so the assts described by eqs. (25) and (26)
are equivalent to eq. (2). Therefore the
Euler theory (2) is merely a re-expression
of an equation of type (12).
